## **XPT**<sup>™</sup> For remotec andros F6A



MOTEC ANDROS

The XPT<sup>™</sup> high-fidelity training system utilizes state-of-the-art virtual simulation with game quality graphics. The full physics engine emulates complete motion and physical interaction of modeled robot, 3D models, and the synthetic environment.



REMOTEC ANDROS

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TALON

CAND

**XPT**<sup>TM</sup>

**FOR TALON** 







## XPT

- High Fidelity Training System Utilizing State of the Art Virtual Simulation with Game Quality Graphics
- Full Physics Engine
  - Emulates Complete Movement of the Actual Robot
  - Emulates Stand Alone Objects in the Virtual Environment
- Scenario Based Training
- Train Like You Operate Operate Like You Trained - Operate Robot in Realistic Simulated Environments

## **XPT<sup>™</sup> FEATURES**

- Fully Integrated Trainer
  - Uses Actual or Emulated Operator Controller Units (OCUs) - USB Cable Connects OCU to Laptop
  - -- Integrated Cable Ships with Trainer (if required)
  - All Controls Fully Enabled
  - All Menus Enabled
    - -- Detailed Menus Exactly Like Actual Robot
  - Fully Enabled Soft Panel Display
    - -- Digital Version of OCU
    - -- All Buttons, Toggle Switches, and Dials Fully Enabled
- Physics Engine Enabled
  - Real Life Movement Based on Actual Mass/Weight Properties of Robot

## ADDITIONAL FEATURES

- Contract to Build Specific Building Structures
- Contract to Build Your Specific Training Environment
  - Realistic Environments
    - Urban/Suburban/Rural
    - Room Interiors
    - Complete Library of 3D Objects
      - -- Cars
      - -- Trucks
      - -- Mailboxes
      - -- Barriers
      - -- Cones...and many others
  - Environmental Effects
  - Time of Day
  - Shadow Casting
  - Rain/Snow/Fog (Visual Obscurants)

- Multiple Camera Views
  - Surveillance Camera Arm
  - Drive Camera
  - 3rd Person View for Training Purposes
  - Rotate Eyepoint 360 Degrees Around Robot
  - IR Camera View
  - Picture-In-Picture/Split Screen View
- Fully Integrated Audio
  - Realistic Sounds Depict Actual Operation of Robot
- Step Motors
- Drive Speeds
- Brake Solenoids



- Bypass Wear and Tear on Actual Robot -- No Broken Cameras
  - -- No Thrown Tracks
  - -- Increased Stick Time Without Negative Results

- 3D Objects Also Have Actual Physics Properties -- Move Cones and Open Doors
  - -- Obstruct Movement with Larger Items
- Real Life Contact with Simulated Environment
- -- Climb Stairs

- -- Roll Over Curbs -- Push Objects Around
  - -- Move and Grab Objects
  - -- Open Doors
  - -- Open Mailboxes
  - -- Grab Pipe Bombs